Possibilistic vs Evidential Valuation Algebra Networks

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Australian Government

Department of Defence Science and Technology

9th October 2019

Outline

Realistic Reasoning Applications

- Heterogeneous data, various types of uncertainty, multiple variables
- Illustrative example \longrightarrow The Captain's Decision Problem

2 Approaches to Modelling Uncertainty

- Handling multiple variables → Valuation Based Algebra (VBA)
- Beyond probability theory \longrightarrow Possibility theory, DS evidence theory

3 New Possibilistic Valuation Algebra Network

- Valuations as Possibility Functions
- VBA Operations adhere to Possibility Theory
- Possibilistic Uncertain Implication Rule
- 4 Simulation Results

5 Conclusions

Uncertain Reasoning Captain's Problem

Real World Reasoning and Decision Making...

Some challenges:

Data

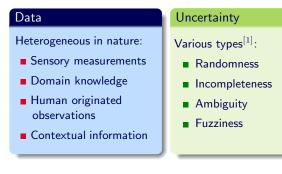
Heterogeneous in nature:

- Sensory measurements
- Domain knowledge
- Human originated observations
- Contextual information

Uncertain Reasoning Captain's Problem

Real World Reasoning and Decision Making...

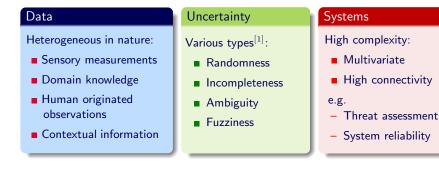
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Real World Reasoning and Decision Making...

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Real World Reasoning and Decision Making...

Some challenges:

Data	Uncertainty	Systems	
 Heterogeneous in nature: Sensory measurements Domain knowledge Human originated observations Contextual information 	Various types ^[1] : Randomness Incompleteness Ambiguity Fuzziness	 High complexity: Multivariate High connectivity e.g. Threat assessment System reliability 	

Our approach:

- $\stackrel{ }{\mapsto} \ \ Construct\ reasoning\ networks\ using\ different\ models\ of\ uncertainty} e.g.\ Possibility\ Theory\ and\ Dempster-Shafer\ Evidence\ Theory}$

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Uncertain Reasoning Captain's Problem

An example - The Captain's Decision Problem^[1]

Estimate the number of days a ship will be delayed based on the following

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Additional Information

- **5** Chance of 1 day loading delay is 30% to 50%.
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Modelling Systems Quantifying Uncertaint

Valuation Based Algebra^[1]

A framework for representing knowledge and inferring outcomes within a system

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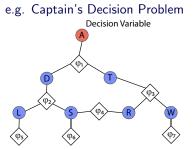
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Valuation Based Algebra^[1]

A framework for representing knowledge and inferring outcomes within a system

Primary Elements:

- 1 Variables V within the system
- **2** Valuation functions φ



Valuations represent knowledge about the relationship between variables

Notation: $\Theta_{\mathcal{D}} = \text{set of possible values of a set of variables } \mathcal{D}$ $\hookrightarrow = \text{Configurations of } \mathcal{D}$

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Modelling Systems Quantifying Uncertainty

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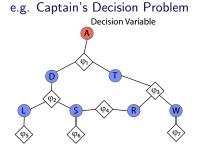
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Operations for inferring outcomes:

- 1 Combination \oplus
- 2 Marginalization \downarrow



Combination is the aggregation of knowledge

e.g. $arphi_2\oplusarphi_5=$ aggregated knowledge from $arphi_2$ and $arphi_5$

Marginalization is the focusing of knowledge e.g. $\varphi_2^{\downarrow D} =$ knowledge of D implied by φ_2 if other variables disregarded. [1] P. Shenov, 'A valuation-based language for expert systems', Int. J. Approx. Reason., 1989.

Modelling Systems Quantifying Uncertainty

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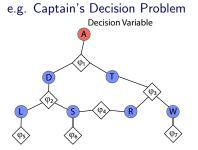
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 $\begin{array}{l} \mbox{Inference} = \mbox{Successive application of combination \& marginalization} \\ & \oplus \ \mbox{e.g. end goal is to obtain } (\varphi_1 \oplus \varphi_2 \oplus \ldots \oplus \varphi_7)^{\downarrow A} \end{array}$

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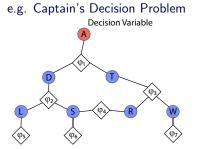
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If $\{\oplus,\downarrow\}$ satisfy a set of axioms^[2] = marginal can be computed locally!

[2] P. Shenoy and G. Shafer, 'Axioms for probability and belief-function propagation', in Readings in uncertain reasoning, 1990.

Quantifying Uncertainty in a System

 $\, \hookrightarrow \,$ Specifying the valuation functions and the operations \oplus, \downarrow

Many approaches to modeling uncertainty:

- Probability theory
- Possibility theory^[1]
- Imprecise probabilities^[2]
- Random sets^[3]
- Dempster-Shafer (DS) evidence theory^[4,5]

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- [4] A. Dempster, 'Upper and lower probabilities induced by a multivalued mapping', Annals Math. Stat., 1967.
- [5] G. Shafer, 'A mathematical theory of evidence', Princeton Uni. Press, 1976.
- [6] A. Benavoli et. al., 'An application of evidential networks to threat assessment', IEEE Trans. Aerosp. Electron. Syst., 2009

Possibilistic vs Evidential Networks

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Compare two approaches:

VBA using DS evidence theory \implies Evidential Networks^[6] VBA using Possibility theory \implies Possibilistic Networks **(our focus)**

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Possibility Theory Possibilistic Networks Implication Rule

Recap on Zadeh's Possibility Theory

Principle of minimal specificity

Unless impossible, no hypothesis can be ruled out

Measuring Possibility

Given a set of variables $\mathcal D$ with configurations $\Theta_{\mathcal D}$:

 \hookrightarrow possibility of an event $A \subseteq \Theta_{\mathcal{D}}$ is the mapping $\Pi : 2^{\Theta_{\mathcal{D}}} \to [0,1]$ where $2^{\Theta_{\mathcal{D}}}$ is the power set of $\Theta_{\mathcal{D}}$.

Π satisfies:

- **1** $\Pi(\varnothing) = 0 \rightarrow \Theta_{\mathcal{D}}$ is an exhaustive set of configurations
- 2 $\Pi(\Theta_{\mathcal{D}}) = 1 \rightarrow \text{mapping } \Pi \text{ is free of contradictions}$
- 3 $\Pi(A_1 \cup A_2) = \max(\Pi(A_1), \Pi(A_2)) \rightarrow$ replaces the additivity axiom in probability theory.

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Concept of Necessity N:

Necessity is the dual of possibility such that $N(A)=1-\Pi(A^c), \ \, {\rm where} \ \, A^c \ {\rm is \ the \ complement \ of} \ \, A$

Possibility Theory Possibilistic Networks Implication Rule

Possibility Functions

Possibility Functions

$$\begin{array}{l} \text{A function } \pi: \Theta_{\mathcal{D}} \to [0,1] \text{ such that, for } A \subseteq \Theta_{\mathcal{D}}: \\ \Pi(A) = \max_{x \in A} \pi(x) \quad \text{and} \quad N(A) = \min_{x \in A^c} (1 - \pi(x)) \end{array}$$

Properties:

- $\pi(x) = 1$ for $x = x_0$ and 0 otherwise \implies Complete knowledge
- $\pi(x) = 1, \ \forall x \in \Theta_{\mathcal{D}} \implies$ Complete ignorance

Possibility Theory Possibilistic Networks Implication Rule

Possibility Functions

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Relationship to a probability function p(x):

$$\pi(x) = \frac{p(x)}{\max_{x \in \Theta_{\mathcal{D}}} p(x)} \iff p(x) = \frac{\pi(x)}{\sum_{x \in \Theta_{\mathcal{D}}} \pi(x)}$$

Possibility Theory Possibilistic Networks Implication Rule

Possibilistic Networks

Key Concepts:

Valuation functions = Possibility functions Operations adhere to Possibility Theory

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Possibilistic Combination^[1]:

Given $\pi_1^{\mathcal{D}}$ and $\pi_2^{\mathcal{D}}$ representing valuations φ_1 and φ_2 then:

$$\left(\pi_1^{\mathcal{D}} \oplus \pi_2^{\mathcal{D}}\right)(a) = \frac{\pi_1^{\mathcal{D}}(a) \cdot \pi_2^{\mathcal{D}}(a)}{\max_{a \in \Theta_{\mathcal{D}}} \left\{\pi_1^{\mathcal{D}}(a) \cdot \pi_2^{\mathcal{D}}(a)\right\}}, \quad \forall \quad a \in \Theta_{\mathcal{D}}$$

Possibilistic Marginalization^[1]:

Given $\pi^{\mathcal{D}}$ then marginalization onto a coarser domain $\mathcal{D}' \subseteq \mathcal{D}$ is: $\pi^{\downarrow \mathcal{D}'}(a) = \max_{b \in \Theta_{\mathcal{D}}} \left\{ \pi^{\mathcal{D}}(a, b) \right\}, \quad \forall \quad a \in \Theta_{\mathcal{D}'}.$

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$\, \hookrightarrow \,$ Operations satisfy axioms for local computation

Possibility Theory Possibilistic Networks Implication Rule

Possibilistic Uncertain Implication Rules

Given outcomes $a \in \Theta_{\mathcal{D}_1}$ and $b \in \Theta_{\mathcal{D}_2}$:

Rule allows evaluation of expert knowledge of the form "if a then b" with an associated confidence level $[\alpha, \beta]$, where $0 \le \alpha \le \beta \le 1$.

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We formulate possibilistic rule based on:

- If $a^c \implies$ Complete ignorance on outcomes in $\Theta_{\mathcal{D}_2}$
- If a and $b \implies$ Confidence in outcome $\max([\alpha, \beta]) = \beta$
- If a and $b^c \implies \text{Confidence in outcome } \max([1-\beta, 1-\alpha]) = 1-\alpha$
- Normalise outcomes dependent on a

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Thus we propose:

$$\pi_R^{\mathcal{D}_1 \times \mathcal{D}_2}(c) = \begin{cases} \beta K^{-1} & \text{if } c = a \times b\\ (1 - \alpha) K^{-1} & \text{if } c = a \times b^c\\ 1 & \text{if } c = a^c \times \Theta_{\mathcal{D}_2} \end{cases}$$

where $K = \max(\beta, 1 - \alpha)$ and \times represents the Cartesian product.

Comparing Networks using the Captain's Problem

Scenario A - using only prior information:

Prior Information

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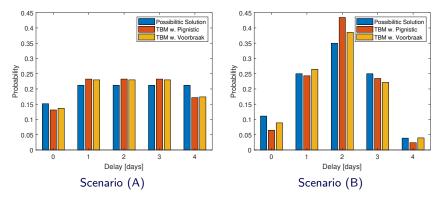
Scenario B - using prior and additional information:

Additional Information

- **5** Chance of 1 day loading delay is 30% to 50%.
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Results - Scenarios A & B

Comparing possibilistic and evidential networks:

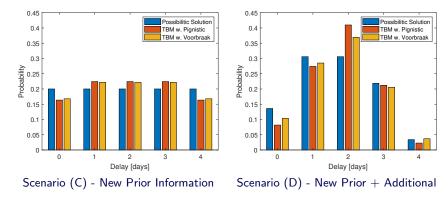


 \hookrightarrow Prior information fairly uninformative on its own Using additional information \implies All networks predict 2 days delay

TBM w. Pignistic = evidential network using Pignistic transform TBM w. Voorbraak = evidential network using Voorbraak transform

Results - Probing Network Performance

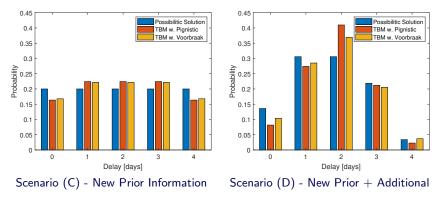
Change implication rule in the prior information:



 $\, \leftrightarrow \,$ A repair is required 30% to 70% of the trips if no service

Results - Probing Network Performance

Change implication rule in the prior information:



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 \hookrightarrow Change in prediction for the possibilistic network

Further Analysis...

Determine the probability of requiring a repair at set by analysing the local network relating S and R:

VBS Network	Scenario (B)		Scenario (D)	
	Repair	No Repair	Repair	No Repair
Possibilistic Evidential with Pignistic Evidential with Voorbraak	$0.583 \\ 0.750 \\ 0.667$	$0.417 \\ 0.250 \\ 0.333$	$0.500 \\ 0.650 \\ 0.588$	$0.500 \\ 0.350 \\ 0.412$

 $\, \hookrightarrow \,$ Difference in behaviour due to uncertain implication rule

Conclusions & Future Work

Conclusions

- Focus on reasoning in uncertain multivariate systems
 - \blacksquare Model system \implies Valuation base algebra framework
 - \blacksquare Model uncertainty \implies Possibility theory or DS evidence theory
- Presented possibilistic VBA network
 - Valuations and operations adhere to Possibility theory
 - Proposed possibilistic uncertain implication rule
- Compared evidential & possibilistic networks on Captain's Problem
 - Possibilistic network sensitive to changes in implication rule

Future Work

Open problem:

 $\hookrightarrow~$ Develop a framework for evaluating VBS networks



Thank you for listening